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HP 64785

# SH-7000 Emulator Softkey Interface

## User's Guide



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## Printing History

New editions are complete revisions of the manual. The date on the title page changes only when a new edition is published.

A software code may be printed before the date; this indicates the version level of the software product at the time the manual was issued. Many product updates and fixes do not require manual changes and, manual corrections may be done without accompanying product changes. Therefore, do not expect a one-to-one correspondence between product updates and manual revisions.

**Edition 1            64785-97001, June 1994**

# Using this Manual

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This manual shows you how to use the following emulators with the Softkey Interface.

- HP 64785A SH-7000 emulator

This manual:

- Shows you how to use emulation commands by executing them on a sample program and describing their results.
- Shows you how to use the emulator in-circuit (connected to a demo board/target system).
- Shows you how to configure the emulator for your development needs. Topics include: restricting the emulator to real-time execution.

This manual does not:

- Show you how to use every Softkey Interface command and option; the Softkey Interface is described in the *Softkey Interface Reference* manual.

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## Organization

- Chapter 1** **Introduction to the SH-7000 Emulator.** This chapter briefly introduces you to the concept of emulation and lists the basic features of the SH-7000 emulator.
- Chapter 2** **Getting Started.** This chapter shows you how to use emulation commands by executing them on a sample program. This chapter describes the sample program and how to: load programs into the emulator, map memory, display and modify memory, display registers, step through program, run programs, set software breakpoints, search memory for data, and use the analyzer.
- Chapter 3** **"In-Circuit" Emulation.** This chapter shows you how to install the emulator probe into a demo board and target system and how to use "in-circuit" emulation features.
- Chapter 4** **Configuring the Emulator.** This chapter shows you how to: restrict the emulator to real-time execution, allow the target system to insert wait states, and select foreground or background monitor.
- Chapter 5** **Using the Emulator.** This chapter describes emulation topics which are not covered in the "Getting Started" chapter.

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## Conventions

Example commands throughout the manual use the following conventions:

<b>bold</b>	Commands, options, and parts of command syntax.
<b><i>bold italic</i></b>	Commands, options, and parts of command syntax which may be entered by pressing softkey.
normal	User specified parts of a command.
\$	Represents the HP-UX prompt. Commands which follow the "\$" are entered at the HP-UX prompt.
<RETURN>	The carriage return key.



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# Introduction to the SH-7000 Emulator

---

## Introduction

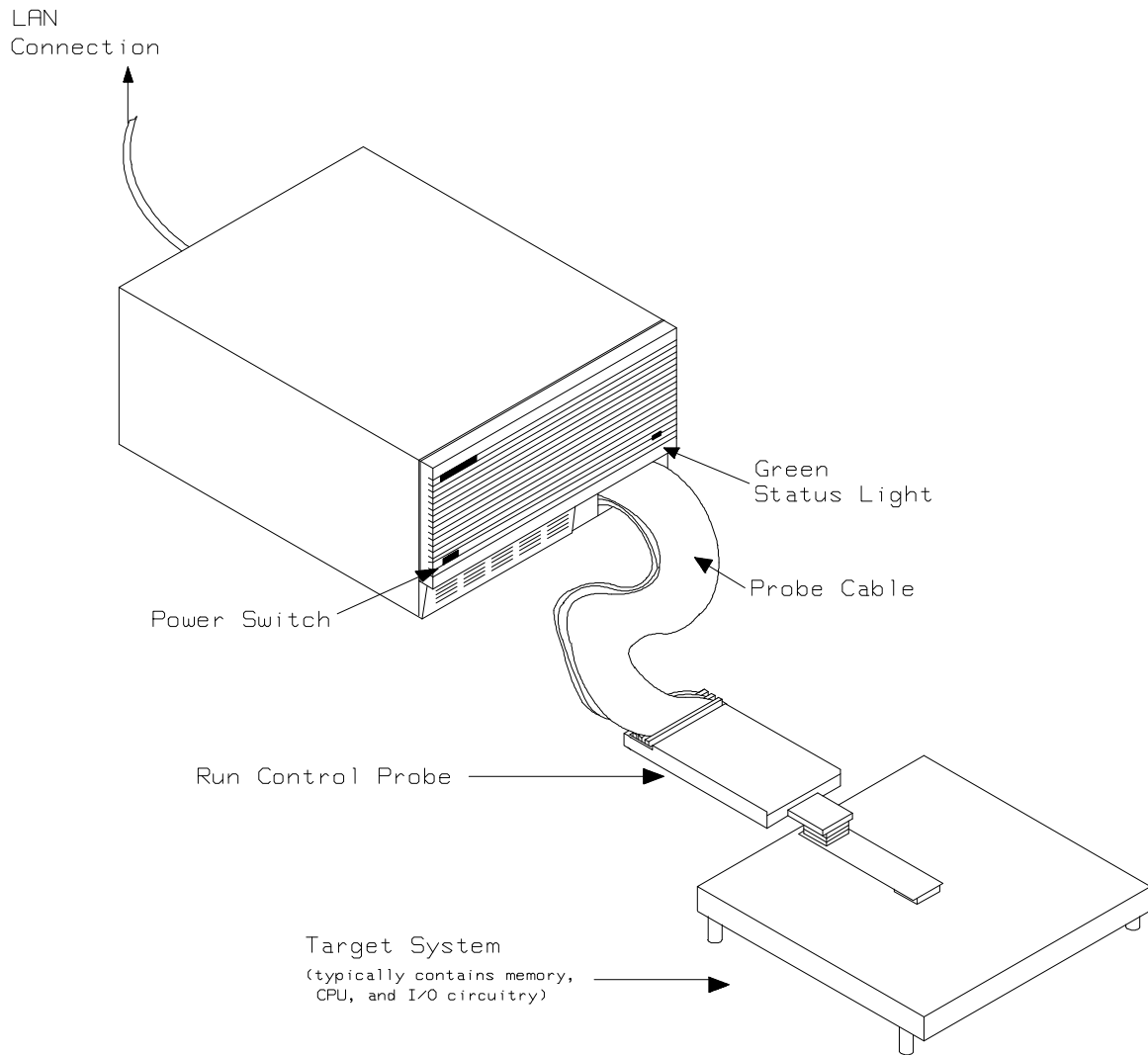
The topics in this chapter include:

- Purpose of the emulator
- Features of the emulator
- Limitations and Restrictions of the SH-7000 emulator

---

## Purpose of the Emulator

The SH-7000 emulator is designed to replace the SH-7000 microprocessor series in your target system to help you debug/integrate target system software and hardware. The emulator performs just like the processor which it replaces, but at the same time, it gives you information about the bus cycle operation of the processor. The emulator gives you control over target system execution and allows you to view or modify the contents of processor registers, target system memory.



**Figure 1-1 HP 64785A Emulator for SH-7000**

**1-2 Introduction**

---

## Features of the SH-7000 Emulator

This section introduces you to the features of the emulator. The chapters which follow show you how to use these features.

### Supported Microprocessors

The SH-7000 emulator supports the microprocessors listed in Table 1-1.

**Table 1-1 Supported Microprocessors**

Supported Microprocessors	Referred to as
HD6417032F	SH-7032
HD6477034F HD6437034F	SH-7034

### Clock Speeds

The SH-7000 emulator runs with a target system clock from 2.0 to 20.0 MHz.

### Emulation memory

The SH-7000 emulator can be used with one of the following Emulation Memory Module.

- HP 64172A 256K byte 20ns Emulation Memory Module
- HP 64172B 1M byte 20ns Emulation Memory Module
- HP 64173A 4M byte 25ns Emulation Memory Module

You can define up to 16 memory ranges. The minimum amount of emulation memory that can be allocated to a range is 16K byte. You can characterize memory ranges as emulation RAM, emulation ROM, target system RAM, target system ROM, or guarded memory. The emulator generates an error message when accesses are made to guarded memory locations. You can also configure the emulator so that writes to memory defined as ROM cause emulator execution to break out of target program execution. Refer to the "Memory Mapping" section in the "Using the emulator" chapter.



**Analysis** The SH-7000 emulator is used with one of the following analyzers which allows you to trace code execution and processor activity.

- HP64704 80-channel Emulation Bus Analyzer
- HP64794A/C/D Deep Emulation Bus Analyzer

The Emulation Bus Analyzer monitors the emulation processor using an internal analysis bus.

**Registers** You can display or modify the SH-7000 internal register contents. This includes the ability to modify the program counter(PC) value so you can control where the emulator starts program run.

**Emulation Monitor** The emulation monitor is a program that is executed by the emulation processor. It allows the emulation controller to access target system resources, and emulation memory. For example, when you display target system memory, it is monitor program that executes SH-7000 instructions which read the target memory locations and send their contents to the emulation controller.

**Single-Step** You can direct the emulation processor to execute a single instruction or a specified number of instructions.

**Breakpoints** You can set up the emulator/analyzer interaction so the emulator break to the monitor program when the analyzer finds a specific state or states, allowing you to perform post-mortem analysis of the program execution. You can also set software breakpoints in your program. This feature is realized by inserting a special instruction into user program. One of undefined opcodes (0000 hex) is used as software breakpoint instruction. Refer to the "Using Software Breakpoints" section of "Getting Started" chapter for more information.

**Reset Support** The emulator can be reset from the emulation system under your control, or your target system can reset the emulation processor.

**Real-Time Operation** Real-time operation signifies continuous execution of your program without interference from the emulator. (Such interference occurs when the emulator needs to break to the monitor to perform an action you requested, such as displaying target system memory.) The Emulator features performed in real-time include: running and analyzer tracing.

The emulator features not performed in real-time includes: display or modification of target system memory, load/dump of target memory, display or modification of registers.

**Coverage and  
Memory Copy**

The SH-7000 emulator does not support coverage test and memory copy from target memory.

**Easy Products  
Upgrades**

Because the HP 64700 Series development tools (emulator, analyzer, LAN board) contain programmable parts, it is possible to reprogram the firmware and some of the hardware without disassembling the HP 64700B Card Cage. This means that you'll be able to update product firmware, if desired, without having to call an HP field representative to your site.

---

## Limitations, Restrictions

### Interrupts While in the Monitor

The SH-7000 emulator does not accept any interrupts in the monitor program. Edge sensed interrupts are suspended while running the monitor program, and such interrupts will occur when context is changed to the user program. Level sensed interrupts are ignored during the monitor program.

BREQ signal is always accepted by the SH-7000 emulator.

### Watchdog Timer

The watchdog timer is suspended count up while the emulator is running the monitor program.

### Monitor Break at Sleep/Standby Mode

When the SH-7000 emulator breaks into the monitor program, sleep or software standby mode is released. Then, PC indicates next address of "SLEEP" instruction.

### Memory Module

One state access and DRAM short pitch access are not allowed, when you operate the emulator using 25ns memory module with the clock faster than 16.6MHz.

One state access is not allowed, when you operate the emulator using 20ns memory module with the target system which uses BREQ signal and the clock faster than 16.6MHz.

### DMA support

Direct memory access to the emulation memory by external DMAC is not allowed.

Single address mode transfer to the emulation memory by internal DMAC is not allowed.

### Warp Mode

SH-7000 emulator does not support Warp mode.

### Evaluation Chip

Hewlett-Packard makes no warranty of the problem caused by the SH-7000 Evaluation chip in the emulator.

## Getting Started

---

### Introduction

This chapter will lead you through a basic, step by step tutorial that shows how to use the HP 64785A SH-7000 emulator (for the SH-7032/34 microprocessor) with the Softkey Interface.

This chapter will:

- Tell you what must be done before you can use the emulator as shown in the tutorial examples.
- Describe the demo program used for this chapter's examples.

This chapter will show you how to:

- Start up the Softkey Interface.
- Load programs into emulation and target system memory.
- Enter emulation commands to view execution of the demo program.

---

## Before You Begin

### Prerequisites

Before beginning the tutorial presented in this chapter, you must have completed the following tasks:

1. Connected the emulator to your computer. The *HP 64700 Series Installation/Service* manual show you how to do this.
2. Installed the Softkey Interface software on your computer. Refer to the *HP 64700 Series Installation/Service* manual for instructions on installing software.
3. In addition, you should read and understand the concepts of emulation presented in the *Concepts of Emulation and Analysis* manual. The *Installation/Service* manual also covers HP 64700 system architecture. A brief understanding of these concepts may help avoid questions later.

You should read the *Softkey Interface Reference* manual to learn how to use the Softkey Interface in general. For the most part, this manual contains information specific to the SH-7000 emulator.

### A Look at the Demo Program

The demo program is *spmt\_demo* consisting of source program *spmt\_demo.c* and *init.src*.

#### Where is the *spmt\_demo* Software?

The demo program is shipped with the Softkey Interface and may be copied from the following directory.

**`/usr/hp64000/demo/emul/hp64785`**

## Compiling the Demo Program

The demo program is written for and compiled/linked with the Hitachi SH7000 C Compiler Package. The demo program was compiled with the following command.

```
$ shc -debug spmt_demo.c <RETURN>
$ asmsh -debug init.src <RETURN>
```

## Linking the Demo Program

The following command was used to generate the absolute file. The contents of "spmt\_demo.k" linkage editor subcommand file is shown in figure 2-1.

```
$ lnk -subcommand=spmt_demo.k<RETURN>
```

```
debug
input spmt_demo,init
library shclib.lib
start P(1000),B(0F000000)
output spmt_demo
print spmt_demo
exit
```

Figure 2-1 Linkage Editor Subcommand File

## Generate HP Absolute file

To generate HP Absolute file for the Softkey Interface, you need to use "shcnvhp" absolute file format converter program. The shcnvhp converter is provided with HP 64785 Softkey Interface. To generate HP Absolute file, enter following command:

```
$ shcnvhp spmt_demo <RETURN>
```

You will see that spmt\_demo.X, spmt\_demo.L, and spmt\_demo.A are generated. These are sufficient throughout this chapter.

## Note



---

You need to specify "debug" command line option to compiler, assembler and linker command to generate local symbol information.

---

---

## Entering the Softkey Interface

If you have installed your emulator and Softkey Interface software as directed in the *HP 64700 Series Emulators Softkey Interface Installation Notice*, you are ready to enter the interface. The Softkey Interface can be entered from the HP-UX shell.

### From the HP-UX Shell

If `/usr/hp64000/bin` is specified in your PATH environment variable, you can also enter the Softkey Interface with the following command.

```
$ emul1700 <emul_name> <RETURN>
```

The "emul\_name" in the command above is the logical emulator name given in the HP 64700 emulator device table (`/usr/hp64000/etc/64700tab.net`).

```
#-----+-----+-----+-----+
# Channel | Logical | Processor | Remainder of Information for the Channel
# Type   | Name   | Type     | (IP address for LAN connections)
#-----+-----+-----+-----+
# lan:   | sh70  | sh7034   | 21.17.9.143
```

If this command is successful, you will see a display similar to figure 2-2. The status message shows that the default configuration file has been loaded. If the command is not successful, you will be given an error message and returned to the HP-UX prompt. Error messages are described in the *Softkey Interface Reference* manual.

```

HPB3076-11001 A.05.20 17Mar94
SH7032/34 SOFTKEY USER INTERFACE

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STATUS: Starting new session_____...R....

run trace step display modify break end ---ETC--

```

**Figure 2-2 Softkey Interface Display**

### **Configure the Emulator for Examples**

To do operations described in this chapter (loading absolute program into emulation memory, displaying memory contents, etc), you need to configure the emulator as below. For detailed description of each configuration option (question), refer to the "*Configuring the Emulator*" chapter.

To get into the configuration session of the emulator, enter the following command.

***modify configuration*** <RETURN>

Answer to the series of questions as below.

```

Restrict to real-time runs? no <RETURN>
Processor type? 7032 <RETURN>
Processor operation mode? mode_0 <RETURN>
Area 1 memory type? other <RETURN>
Modify memory configuration? yes <RETURN>

```

Now you should be facing memory mapping screen. One mapper term must be specified for the demo program. Enter the following line to map the program code.



```
0h thru 3fffh emulation rom <RETURN>
end <RETURN>
Modify emulator pod configuration? no <RETURN>
Modify debug/trace options? no <RETURN>
Modify simulated I/O configuration? no <RETURN>
Modify interactive measurement specification? no <RETURN>
```

If you wish to save the configuration specified above, answer this question as shown.

```
Configuration file name? spmt_demo <RETURN>
```

Now you are ready to go ahead. Above configuration is used throughout this chapter.

## Note



---

The internal RAM/ROM area and emulation monitor area are mapped automatically. And the emulation memory system does not introduce internal RAM/ROM area in memory mapping display.

---

---

## On-Line Help

There are two ways to access on-line help in the Softkey Interface. The first is by using the Softkey Interface help facility. The second method allows you to access the firmware resident Terminal Interface on-line help information.

### Softkey Driven Help

To access the Softkey Interface on-line help information, type either "help" or "?" on the command line; you will notice a new set of softkeys. By pressing one of these softkeys and <RETURN>, you can cause information on that topic to be displayed on your screen. For example, you can enter the following command to access "system command" help information.

```
? system_commands <RETURN>
```

```

---SYSTEM COMMANDS & COMMAND FILES---

?                displays the possible help files
help             displays the possible help files

!                fork a shell (specified by shell variable SH)
!<shell command> fork a shell and execute a shell command

pwd             print the working directory
cd <directory>  change the working directory

pws            print the default symbol scope
cws <SYMB>      change the working symbol - the working symbol also
                gets updated when displaying local symbols and
                displaying memory mnemonic

forward <UI> "command" send the command in the quoted string from this user
                interface to another one. Replace <UI> with the name
                of the other user interface as shown on the softkeys:

--More--(15%)

```

The help information is scrolled on to the screen. If there is more than a screenful of information, you will have to press the space bar to see the next screenful, or the <RETURN> key to see the next line, just as you do with the HP-UX **more** command. After all the information on the particular topic has been displayed (or after you press "q" to quit scrolling through information), you are prompted to press <RETURN> to return to the Softkey Interface.

### Pod Command Help

To access the emulator's firmware resident Terminal Interface help information, you can use the following commands.

```

display pod_command <RETURN>
pod_command 'help cf' <RETURN>

```

```

Pod Commands
Time          Command
cf <item> <item>=<value> <item> - set and display can be combined

help cf <item> - display long help for specified <item>

--- VALID CONFIGURATION <item> NAMES ---
areal - specify memory type of area 1
bpds - en/dis setting software breakpoints at delay slot
breq - specify function of PA8/BREQ pin
chip - select emulation processor
mode - select processor operation mode
qbrk - en/dis quick temporary break to monitor
rrt - en/dis restriction to real time runs
rsp - specify stack pointer after emulation reset
tdma - en/dis tracing of on-chip DMAC cycles
trfsh - en/dis tracing of refresh cycles

STATUS: SH7032--Emulation reset_____...R....
pod_command 'help cf'

run      trace      step      display      modify      break      end      ---ETC--

```

The command enclosed in string delimiters (" , ' or ^) is any Terminal Interface command, and the output of that command is seen in the pod\_command display. The Terminal Interface help (or ?) command may be used to provide information on any Terminal Interface command or any of the emulator configuration options (as the example command above shows).

## Note




---

If you want to use the Terminal Interface command by entering from keyboard directly, you can do it after entering the following command.

***pod\_command keyboard***

---

---

## Loading Absolute Files

The "load" command allows you to load absolute files into emulation or target system memory. You can load absolute files in the following format:

- HP absolute

The "load" command has no special options for loading different absolute file formats; instead, the contents of the file are examined to determine the format being used. If you wish to load only that portion of the absolute file that resides in memory mapped as emulation RAM or ROM, use the "load emul\_mem" syntax. If you wish to load only the portion of the absolute file that resides in memory mapped as target RAM, use the "load user\_mem" syntax. If you want both emulation and target memory to be loaded, do not specify "emul\_mem" or "user\_mem". For example:

```
load spmt_demo <RETURN>
```

### Note



---

When loading a program if the status line shows

```
"ERROR:      No absolute file, No database:
spmt_demo
```

, you may NOT be in the directory that your program is in. To find out what directory you are in, enter:

```
! pwd <RETURN>
```

The "!" allows you to use an HP-UX shell command. To move into the correct directory, enter:

```
cd <directory path> <RETURN>
```

---

You can also specify the pathname where your program resides. For example, you could enter:

```
load
/usr/hp64000/demo/emul/hp64785/spmt_demo
<RETURN>
```

---

## Displaying Symbols

When you load an absolute file into memory (unless you use the "nosymbols" syntax), symbol information is also loaded. Both global symbols and symbols that are local to a source file can be displayed.

**Global** To display global symbols, enter the following command.

*display global\_symbols* <RETURN>

Listed are address ranges associated with a symbol, the segment that the symbol is associated with, and the offset of that symbol within the segment.

```
Global symbols in spmt_demo.X
Procedure symbols
Procedure name _____ Address range __ Segment _____ Offset
apply_controlle          00014BC - 000151F          04BC
apply_productio          0001364 - 00013CB          0364
calculate_answe          0001520 - 000157F          0520
clear_buffer             000122C - 0001273          022C
endcommand               0001668 - 000166B          0668
format_result           00013CC - 0001413          03CC
get_next_token          0001468 - 00014BB          0468
initialize               0001414 - 0001467          0414
input_line               0001000 - 0001043          0000
lookup_token             0001274 - 00012C7          0274
main                     000166C - 00016C3          066C
math_library             000115C - 00011DB          015C
move_byte                0001044 - 000107B          0044
outputline               00011DC - 000122B          01DC
parse_command            00015C8 - 000161B          05C8

STATUS:  SH7032--Running in monitor_____...R...
display global_symbols

run      trace      step      display      modify      break      end      ---ETC--
```

**Local** When displaying local symbols, you must include the name of the source file in which the symbols are defined. For example,

```
display local_symbols_in spmt_demo.c:  
<RETURN>
```

As you can see, the procedure symbols and static symbols in "spmt\_demo.c" are displayed.

To list the next symbols, press the <PGDN> or <Next> key. the source reference symbols in "spmt\_demo.c" will be displayed.

Listed are: address ranges associated with a symbol, the segment that the symbol is associated with, and the offset of that symbol within the segment.

```
Symbols in spmt_demo.c:  
Procedure symbols  
Procedure name _____ Address range ___ Segment _____ Offset  
apply_controlle 00014BC - 000151F  
apply_productio 0001364 - 00013CB 0364  
calculate_answe 0001520 - 000157F 0520  
clear_buffer 000122C - 0001273 022C  
endcommand 0001668 - 000166B 0668  
format_result 00013CC - 0001413 03CC  
get_next_token 0001468 - 00014BB 0468  
initialize 0001414 - 0001467 0414  
input_line 0001000 - 0001043 0000  
lookup_token 0001274 - 00012C7 0274  
main 000166C - 00016C3 066C  
math_library 000115C - 00011DB 015C  
move_byte 0001044 - 000107B 0044  
outputline 00011DC - 000122B 01DC  
parse_command 00015C8 - 000161B 05C8  
  
STATUS: cws: spmt_demo.c:_____...R....  
display local_symbols_in spmt_demo.c:  
  
run trace step display modify break end ---ETC--
```

## Source Lines

To display the address ranges associated with the program's source file, you must display the local symbols in the file. For example:

```
display local_symbols_in spmt_demo.c:  
<RETURN>
```

And scroll the information down on the display with up arrow, or <Next> key.

```
Symbols in spmt_demo.c:  
Source reference symbols  
Line range _____ Address range __ Segment _____ Offset  
#1-#37                0001000 - 0001001                0000  
#38-#39                0001002 - 0001009                0002  
#40-#40                000100A - 000100F                000A  
#41-#41                0001010 - 0001015                0010  
#42-#42                0001016 - 000101B                0016  
#43-#43                000101C - 0001021                001C  
#44-#44                0001022 - 000102D                0022  
#45-#46                000102E - 0001043                002E  
#47-#51                0001044 - 0001045                0044  
#52-#53                0001046 - 000104D                0046  
#54-#54                000104E - 0001053                004E  
#55-#55                0001054 - 000105F                0054  
#56-#57                0001060 - 0001065                0060  
#58-#58                0001066 - 0001069                0066  
#59-#59                000106A - 000107B                006A  
  
STATUS:   SH7032--Running in monitor_____...R....  
display local_symbols_in spmt_demo.c:  
  
run      trace      step      display      modify      break      end      ---ETC--
```

---

## Displaying Memory in Mnemonic Format

You can display, in mnemonic format, the absolute code in memory.  
For example to display the memory of the demo program,

*display memory main mnemonic* <RETURN>

```
Memory :mnemonic :file = spmt_demo.c:
address  data
000166C  2FE6      MOV.L R14,@-R15
000166E  2FD6      MOV.L R13,@-R15
0001670  4F22      STS.L PR,@-R15
0001672  DD11      MOV.L @(00016B8[,PC]),R13
0001674  DE11      MOV.L @(00016BC[,PC]),R14
0001676  E300      MOV #00,R3
0001678  2E32      MOV.L R3,@R14
000167A  BF81      BSR 0001580
000167C  0009      NOP
000167E  BFA3      BSR 00015C8
0001680  0009      NOP
0001682  61E2      MOV.L @R14,R1
0001684  D30E      MOV.L @(00016C0[,PC]),R3
0001686  430B      JSR @R3
0001688  E005      MOV #05,R0
000168A  7001      ADD #01,R0

STATUS:  SH7032--Running in monitor.....R....
display memory main mnemonic

run      trace      step      display      modify      break      end      ---ETC---
```

Notice that you can use symbols when specifying expressions. The global symbol **main** is used in the command above to specify the starting address of the memory to be displayed.



## Display Memory with Symbols

If you want to see symbol information with displaying memory in mnemonic format, the emulator Softkey Interface provides "set symbols" command. To see symbol information, enter the following command.

**set symbols on** <RETURN>

```
Memory :mnemonic :file = spmt_demo.c:
address  label      data
000166C  :main          2FE6      MOV.L R14,@-R15
000166E                2FD6      MOV.L R13,@-R15
0001670                4F22      STS.L PR,@-R15
0001672                DD11      MOV.L @(:main+000004C[,PC]),R13
0001674                DE11      MOV.L @(:main+0000050[,PC]),R14
0001676                E300      MOV #0,R3
0001678                2E32      MOV.L R3,@R14
000167A                BF81      BSR :request_command
000167C                0009      NOP
000167E                BFA3      BSR :parse_command
0001680                0009      NOP
0001682                61E2      MOV.L @R14,R1
0001684                D30E      MOV.L @(:main+0000054[,PC]),R3
0001686                430B      JSR @R3
0001688                E005      MOV #05,R0
000168A                7001      ADD #01,R0

STATUS:  SH7032--Running in monitor_____...R....
set symbols on

run      trace      step      display      modify      break      end      ---ETC---
```

As you can see, the memory display shows symbol information.

## Display Memory with Source Code

If you want to reference the source line information with displaying memory in mnemonic format, the emulator Softkey Interface provides "set source" command. To reference the source line information in inverse video, enter the following command:

**set source on inverse\_video on** <RETURN>

```
Memory :mnemonic :file = spmt_demo.c:
address label      data
 371
 372  /***** main program *****/
 373
 374  main()
000166C  :main      2FE6      MOV.L R14,@-R15
000166E           2FD6      MOV.L R13,@-R15
0001670           4F22      STS.L PR,@-R15
0001672           DD11      MOV.L @(:main+000004C[,PC]),R13
0001674           DE11      MOV.L @(:main+0000050[,PC]),R14
 375  {
 376           int dummyv;
 377           dummyv = 1;
 378           tasknumber = 0;
0001676           E300      MOV #00,R3
0001678           2E32      MOV.L R3,@R14
 379           while (dummyv == 1)

STATUS:  SH7032--Running in monitor_____...R....
set source on inverse_video on

run      trace      step      display      modify      break      end      ---ETC---
```

To see the memory without source line referencing, enter the following command:

**set source off** <RETURN>

---

## Running the Program

The "run" command lets you execute a program in memory. Entering the "run" command by itself causes the emulator to begin executing at the current program counter address. The "run from" command allows you to specify an address at which execution is to start.

### From Transfer Address

The "run from transfer\_address" command specifies that the emulator start executing at a previously defined "start address". Transfer addresses are defined in assembly language source files with the END assembler directive (i.e., pseudo instruction). Enter:

```
run from transfer_address <RETURN>
```

### From Reset

The "run from reset" command specifies that the emulator begin executing from reset vector as actual microprocessor does.

(See "Running the Emulation from Target Reset" section in the "In-Circuit Emulation" chapter).

---

### Note



Run and step commands from odd address are not allowed. Always you must perform run and step commands from even address.

---

---

### Note



When you perform step command for delayed branch instruction, the emulator steps an instruction in delay slot too.

---

## Displaying Memory

The demo program "spmt\_demo.c" alters memory.

### Using Symbolic Addresses

In the following display, the memory range is displayed using symbolic addresses **data**.

The memory display window is periodically updated. For example, enter the following command:

```
display memory data thru +7fh blocked bytes  
<RETURN>
```

This command string is used to specify the range of memory from **data** to **data+7fh**.

```
Memory :bytes :access=bytes :blocked :update  
address data :hex :ascii  
F00031C-23 00 00 00 07 00 00 00 03 . . . . .  
F000324-2B 00 00 00 01 00 00 00 36 . . . . . 6  
F00032C-33 FF 01 FF FE 00 FF 00 91 . . . . .  
F000334-3B C8 FD 14 11 BF FF 37 FF . . . . . 7 .  
F00033C-43 00 F5 00 80 20 FB 08 C4 . . . . .  
F000344-4B 19 F3 80 E5 F9 25 02 FF . . . . . % . . .  
F00034C-53 80 FA 80 B6 F7 00 FF 7E . . . . . ~  
F000354-5B BE C0 DF 7F 5B 32 82 42 . . . . . [ 2 . B  
F00035C-63 FF C0 EF FC FF 80 FF C9 . . . . .  
F000364-6B F3 20 7A BB 96 02 53 D6 . . z . . S .  
F00036C-73 FF 02 FF FC 80 FF 05 93 . . . . .  
F000374-7B 81 E6 41 27 59 B7 8E 7B . . A ' Y . . {  
F00037C-83 20 09 00 02 40 20 60 48 . . . @ ' H  
F000384-8B 0D 08 70 1D BE 00 F2 1F . . p . . . . .  
F00038C-93 80 80 20 92 FF 7F D5 CF . . . . .  
F000394-9B 83 FF 8D 7F 30 FB 89 30 . . . . . 0 . . 0  
  
STATUS: SH7032--Running user program_____...R....  
display memory data thru +7fh blocked bytes  
  
run trace step display modify break end ---ETC--
```

## Modifying Memory

You can use the modify memory command to send commands to the sample program. Memory locations **stackarea** and **stackarea+10h** correspond to memory address f000004 hex and f000014 hex respectively. For example, to enter the '10h' at address f000004 and enter 'A' at address f000014 : use the following commands.

```
display memory stackarea <RETURN>
modify memory stackarea to 10h <RETURN>
modify memory stackarea+10h string to 'A'
<RETURN>
```

After the memory location are modified, the memory display shows the following

```
Memory :bytes :access=bytes :blocked :update
address      data      :hex      :ascii
F000004-0B   10 FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F00000C-13   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F000014-1B   41 FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F00001C-23   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F000024-2B   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F00002C-33   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F000034-3B   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F00003C-43   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F000044-4B   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F00004C-53   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F000054-5B   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F00005C-63   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F000064-6B   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F00006C-73   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F000074-7B   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
F00007C-83   FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF

STATUS:  SH7032--Running in monitor_____...R....
modify memory stackarea+10h string to 'A'

run      load      step      display      modify      break      end      ---ETC---
```

---

## Breaking into the Monitor

The "break" command allows you to divert emulator execution from the user program to the monitor. You can continue user program execution with the "run" command. To break emulator execution from the demo program to the monitor, enter the following command.

**break** <RETURN>

Notice that the current address is pointed out with inverse video in displaying memory when the execution breaks to the monitor.

### Note



If DMA transfer by internal DMAC is in progress with BURST transfer mode, **break** command is suspended and occurs after DMA transfer is completed.

---

---

## Using Software Breakpoints

Software breakpoints are handled by the SH-7000 undefined instruction (breakpoint interrupt instruction:0000h). When you define or enable a software breakpoint, the emulator will replace the opcode at the software breakpoint address with a breakpoint interrupt instruction.

### Caution



Software breakpoints should not be set, enabled, disabled, or removed while the emulator is running user code. If any of these commands are entered while the emulator is running user code and the emulator is executing code in the area where the breakpoint is being modified, program execution may be unreliable.

---

---

**Note**

A software breakpoint at delay slot causes slot invalid instruction exception in your program.

---

---

**Note**

You must only set software breakpoints at even address. If you set a software breakpoint at odd address, the emulator generates a error.

---

---

**Note**

Because software breakpoints are implemented by replacing opcodes with the breakpoint interrupt instructions, you cannot define software breakpoints in target ROM.

---

When software breakpoints are enabled and the emulator detects the breakpoint interrupt instruction(0000h), it generates a break into the monitor.

If the breakpoint interrupt instruction(0000h) was generated by a software breakpoint, execution breaks to the monitor, and the breakpoint interrupt instruction is replaced by the original opcode. A subsequent run or step command will execute from this address.

If the breakpoint interrupt was generated by a undefined instruction (0000h) in the target program, execution still breaks to the monitor, and an "undefined breakpoint" status message is displayed. To continue program execution, you must run or step from the target program's breakpoint interrupt vector address.

## Enabling/Disabling Software Breakpoints

When you initially enter the Softkey Interface, software breakpoints are disabled. To enable the software breakpoints feature, enter the following command.

```
modify software_breakpoints enable <RETURN>
```

When software breakpoints are enabled and you set a software breakpoint, the SH-7000 breakpoint interrupt instruction (0000h) will

be placed at the address specified. When the breakpoint interrupt instruction is executed, program execution will break into the monitor.

## Setting a Software Breakpoint

To set a software breakpoint at line 80 of "spmt\_demo.c", enter the following command.

```
modify software_breakpoints set line 80  
<RETURN>
```

To see the address where the software breakpoint has been set, enter the following command:

```
display memory line 80 mnemonic <RETURN>  
set source on inverse_video on <RETURN>
```

```
Memory :mnemonic :file = spmt_demo.c:
address label      data
      80          data = 1;
* 00010BE         0000      Illegal Opcode
00010C0         D207      MOV.L @(:scan_number+000002C[ ,PC]),R2
00010C2         2232      MOV.L R3,@R2
      81          stack = 0;
00010C4         E300      MOV #00,R3
00010C6         D207      MOV.L @(:scan_number+0000030[ ,PC]),R2
00010C8         2232      MOV.L R3,@R2
00010CA         E308      MOV #08,R3
00010CC         3433      CMP/GE R3,R4
00010CE         8BF2      BF :scan_number+0000002
      82          }
      83          pre_fetch = 0;
00010D0         E300      MOV #00,R3
00010D2         D205      MOV.L @(:scan_number+0000034[ ,PC]),R2
00010D4         2232      MOV.L R3,@R2

STATUS:  SH7032--Running in monitor_____...R....
display memory line 80 mnemonic

run      trace      step      display      modify      break      end      ---ETC---
```

The asterisk (\*) in left side of the address lists points out that the software breakpoint has been set. The opcode at the software breakpoint address was replaced to the software breakpoint instruction.



## Displaying Software Breakpoints

To display software breakpoints, enter the following command.

```
display software_breakpoints <RETURN>
```

```
Software breakpoints :enabled
address      label
00010BE     spmt_demo.c:
                                line 80  pending

STATUS:  SH7032--Running in monitor.....R....
display software_breakpoints

run      trace    step  display      modify  break    end    ---ETC---
```

The software breakpoints display shows that the breakpoint is pending. When breakpoints are hit they become inactivated. To reactivate the breakpoint so that is "pending", you must reenter the "modify software\_breakpoints set" command.

After the software breakpoint has been set, enter the following command to cause the emulator to continue executing the demo program.

```
run <RETURN>
```

A message on the status line shows that the software breakpoint has been hit. The status line also shows that the emulator is now executing in the monitor.

The software breakpoint address is pointed out with inverse video in displaying memory in mnemonic format. To see the software breakpoint with memory, enter the following command.

```
display memory line 80 mnemonic <RETURN>
```

Notice that the original opcode was replaced at the address that the software breakpoint has been set.

## Clearing a Software Breakpoint

To remove software breakpoint defined above, enter the following command.

```
modify software_breakpoints clear line 80  
<RETURN>
```

The breakpoint is removed from the list, and the original opcode is restored if the breakpoint was pending.

To clear all software breakpoints, you can enter the following command.

```
modify software_breakpoints clear <RETURN>
```

---

## Displaying Registers

Enter the following command to display registers. You can display the basic registers, or an individual register. Refer to "REGISTER CLASS and NAME" section in "Using the Emulator" chapter .

```
display registers <RETURN>
```

```
Registers
Next_PC 00010BE
PC      000010BE      SR 000000F1      t          SP 0F0002F4      PR 00001496
R0-R7  00000003  00000003  0F00031C  00000000  00000001  00000003  00000000  00000000
R8-R15 00000000  00000000  00000000  00000000  00000000  0F000000  00000000  0F0002F4
          GBR 00000000      VBR 00000000      MACH 00000000      MACL 00000000

STATUS:  SH7032--Running in monitor      Software break: 000010be_____...R....
display registers

run      trace      step      display      modify      break      end      ---ETC--
```

## Stepping Through the Program

The step command allows you to step through program execution an instruction or a number of instructions at a time. Also, you can step from the current program counter or from a specific address. To step through the example program from the address of the software breakpoint set earlier, enter the following command.

**step** <RETURN>, <RETURN>, <RETURN>, ...

You will see the inverse-video moves according to the step execution. You can continue to step through the program just by pressing the <RETURN> key.

```
Registers
Next_PC 00010BE
PC      000010BE      SR 000000F1      t      SP 0F0002F4      PR 00001496
R0-R7  00000003  00000003  0F00031C  00000000  00000001  00000003  00000000  00000000
R8-R15 00000000  00000000  00000000  00000000  00000000  0F000000  00000000  0F0002F4
          GBR 00000000      VBR 00000000      MACH 00000000      MACL 00000000

Step_PC 00010BE  MOV #01,R3
Next_PC 00010C0
PC      000010C0      SR 000000F1      t      SP 0F0002F4      PR 00001496
R0-R7  00000003  00000003  0F00031C  00000001  00000001  00000003  00000000  00000000
R8-R15 00000000  00000000  00000000  00000000  00000000  0F000000  00000000  0F0002F4
          GBR 00000000      VBR 00000000      MACH 00000000      MACL 00000000

STATUS:  SH7032--Stepping complete_____...R...
step

run      trace      step      display      modify      break      end      ---ETC---
```

You can step program execution by source lines, enter:

**step source** <RETURN>

Source line stepping is implemented by single stepping assembly instructions until the next PC is outside of the address range of the current source line. When source line stepping is attempted on assembly code, stepping will complete when a source line is found. To terminate stepping type <Ctrl>-C.

**Note**



---

Step and run commands from odd address are not allowed. Always you must perform step and run commands from even address.

---

**Note**



---

When you perform step command for delayed branch instruction, the emulator steps an instruction in delay slot too.

---

---

## Using the Analyzer

HP 64700 emulators contain an emulation analyzer. The emulation analyzer monitors the internal emulation lines (address, data, and status). Optionally, you may have an additional 16 trace signals which monitor external input lines. The analyzer collects data at each pulse of a clock signal, and saves the data (a trace state) if it meets a "storage qualification" condition.

### Source Line Referencing

A trace may be taken and displayed using source line referencing. Also, lines of the source program can be displayed with the trace list where the trace occurred.

To display the trace with source code in inverse video, enter the following command:

```
set source on inverse_video on <RETURN>
```

### Specifying a Simple Trigger

Suppose you want you trace program execution after the point at address **semantic\_check**. The following command make this trace specification.

```
trace after semantic_check <RETURN>
```

The STATUS message shows "Emulation trace started."

Enter the following command to cause sample program execution to continue from the current program counter.

```
run <RETURN>
```

The STATUS message shows "Emulation trace complete."

## Display the Trace

The trace listings which following are of program execution on the SH-7000 emulator. To see the trace list, enter the following command:

**display trace** <RETURN>

```
Trace List   Depth=8192   Offset=0
Label:      Address      Data      Opcode or Status w/ Source Lines   time count
Base:      symbols      hex       mnemonic w/symbols                 relative
after :semantic_check FFFFFFF2F  xxxxxx2F  fetch                               -----
+001  :semanti+0000001 FFFFFFFE6  xxxxxxE6  fetch                               260      nS
+002  :semanti+0000002 FFFFFFF4F  xxxxxx4F  fetch                               240      nS
#####spmt_demo.c - line 201 thru 202 #####
      semantic_check()
      =:semantic_check      MOV.L R14,@-R15
+003  :semanti+0000003 FFFFFFF22  xxxxxx22  fetch                               260      nS
+004  :semanti+0000004 FFFFFFFE4  xxxxxxE4  fetch                               240      nS
      =:semanti+0000002      STS.L PR,@-R15
+005  :semanti+0000005 FFFFFFF00  xxxxxx00  fetch                               260      nS
+006  :spmt_d:+00002F0 00000000  00000000  write long                          40.      nS
+007  :semanti+0000006 FFFFFFFE3  xxxxxxE3  fetch                               260      nS
#####spmt_demo.c - line 203 thru 205 #####
      {
STATUS:  SH7032--Running user program   Emulation trace complete_____...R....
display trace

run      trace      step      display      modify      break      end      ---ETC--
```

The trace list shows the trace after line (semantic\_check()).

To list the next lines of the trace, press the <PGDN> or <NEXT> key.

## Displaying Trace with No Symbol

The trace listing shown above has symbol information because of the "set symbols on" setting before in this chapter. To see the trace listing with no symbol information, enter the following command.

*set symbols off* <RETURN>

Trace List	Depth=8192	Offset=0							
Label:	Address	Data	Opcode	or Status	w/ Source Lines	time count			
Base:	hex	hex		mnemonic		relative			
after	0001310	FFFFFF2F	xxxxxx2F	fetch					
+001	0001311	FFFFFFE6	xxxxxxE6	fetch		260	nS		
+002	0001312	FFFFFF4F	xxxxxx4F	fetch		240	nS		
#####spmt_demo.c - line 201 thru 202 #####									
	semantic_check()								
=	0001310		MOV.L	R14,@-R15					
+003	0001313	FFFFFF22	xxxxxx22	fetch		260	nS		
+004	0001314	FFFFFFE4	xxxxxxE4	fetch		240	nS		
=	0001312		STS.L	PR,@-R15					
+005	0001315	FFFFFF00	xxxxxx00	fetch		260	nS		
+006	F0002F0	00000000	00000000	write long		40.	nS		
+007	0001316	FFFFFFE3	xxxxxxE3	fetch		260	nS		
#####spmt_demo.c - line 203 thru 205 #####									
{									
STATUS: SH7032--Running user program Emulation trace complete.....R....									
set symbols off									
run	trace	step	display	modify	break	end	---	ETC--	

As you can see, the analysis trace display shows the trace list without symbol information.

## Displaying Trace with Compress Mode

If you want to see more executed instructions on a display, the SH-7000 emulator Softkey Interface provides **compress mode** for analysis display. To see trace display with compress mode, enter the following command:

*display trace compress on* <RETURN>

```

Trace List Depth=8192 Offset=0
Label: Address Data Opcode or Status w/ Source Lines time count
Base: hex hex mnemonic relative
#####sfmt_demo.c - line 201 thru 202 #####
semantic_check()
+002 = 0001310 FFFFFFF4F MOV.L R14,@-R15 240 nS
+004 = 0001312 FFFFFFFE4 STS.L PR,@-R15 500 nS
+006 F0002F0 00000000 00000000 write long 300 nS
#####sfmt_demo.c - line 203 thru 205 #####
{
    int i;
    for (i = 0; i < 4; i++)
+007 = 0001314 FFFFFFFE3 MOV #00,R4 260 nS
+009 F0002EC 000014EA 000014EA write long 300 nS
#####sfmt_demo.c - line 206 thru 207 #####
{
    data = 0;

STATUS: SH7032--Running user program Emulation trace complete_____R....
display trace compress on

run trace step display modify break end ---ETC--

```

As you can see, the analysis trace display shows the analysis trace lists without fetch cycles. With this command you can examine program execution easily.

If you want to see all of cycles including fetch cycles, enter following command:

***display trace compress off*** <RETURN>

The trace display shows you all of the cycles the emulation analyzer have captured.

## Emulator Analysis Status Qualifiers

The following analysis status qualifiers may also be used with the SH-7000 emulator.

<u>Qualifier</u>	<u>Status bits</u>	<u>Description</u>
bg	0xxxxxxxxxxxxxxxx0y	Background cycle
byte	0xxxxxxxxx00x0xy	Byte memory cycle
cpu	0xxxxxxxxxxxx1xxy	CPU cycle
data	0xxxxxxxxxxxx0xy	Data cycle
dma	0xxxxxxxxx00xy	DMA cycle
fetch	0xxxxxxxxx111xy	Fetch cycle
fg	0xxxxxxxxxxxxx1y	Foreground cycle
grd	00xxxxxxxxxxxxxy	Guarded memory access
intack	0x0xxxxxxxx111xy	Interrupt acknowledge cycle
long	0xxxxxxxxx101xxy	Long word access
read	0xxxxxxxxxxxx1xy	Read cycle
refresh	0xxxxxxxxx01xxy	Refresh cycle
word	0xxxxxxxxx01xxy	Word access
write	0xxxxxxxxx00xy	Write cycle
wrrom	0x0xxxxxxxx00xy	Write to ROM cycle

## For a Complete Description

For a complete description of using the HP 64700 Series analyzer with the Softkey Interface, refer to the *Analyzer Softkey Interface User's Guide*.

---

## Resetting the Emulator

To reset the emulator, enter the following command.

```
reset <RETURN>
```



---

## Exiting the Softkey Interface

There are several options available when exiting the Softkey Interface: exiting and releasing the emulation system, exiting with the intent of reentering (continuing), exiting locked from multiple emulation windows, and exiting (locked) and selecting the measurement system display or another module.

### End Release System

To exit the Softkey Interface, releasing the emulator so that other users may use the emulator, enter the following command.

```
end release_system <RETURN>
```

### Ending to Continue Later

You may also exit the Softkey Interface without specifying any options; this causes the emulator to be locked. When the emulator is locked, other users are prevented from using it and the emulator configuration is saved so that it can be restored the next time you enter (continue) the Softkey Interface.

```
end <RETURN>
```

### Ending Locked from All Windows

When using the Softkey Interface from within window systems, the "end" command with no options causes an exit only in that window. To end locked from all windows, enter the following command.

```
end locked <RETURN>
```

This option only appears when you enter the Softkey Interface via the **emul700** command. When you enter the Softkey Interface via **pmon** and **MEAS\_SYS**, only one window is permitted.

Refer to the *Softkey Interface Reference* manual for more information on using the Softkey Interface with window systems.

### Selecting the Measurement System Display or Another Module

When you enter the Softkey Interface via **pmon** and **MEAS\_SYS**, you have the option to select the measurement system display or another module in the measurement system when exiting the Softkey Interface. This type of exit is also "locked"; that is, you can continue the emulation session later. For example, to exit and select the measurement system display, enter the following command.

```
end select measurement_system <RETURN>
```

This option is not available if you have entered the Softkey Interface via the **emul700** command.

---

## Notes

## In-Circuit Emulation Topics

---

### Introduction

Many of the topics described in this chapter involve the installation, and the commands which relate to using the emulator in-circuit, that is, connected to a target system or demo target board.

This chapter will:

- Show you how to install the emulation probe cable
- Show you how to install the emulation memory module.
- Show you how to install the emulation probe to demo target board.
- Describe the issues concerning the installation of the emulation probe into target systems.
- Describe how to execute program from target reset. This topics is related to program execution in general.

---

### Prerequisites

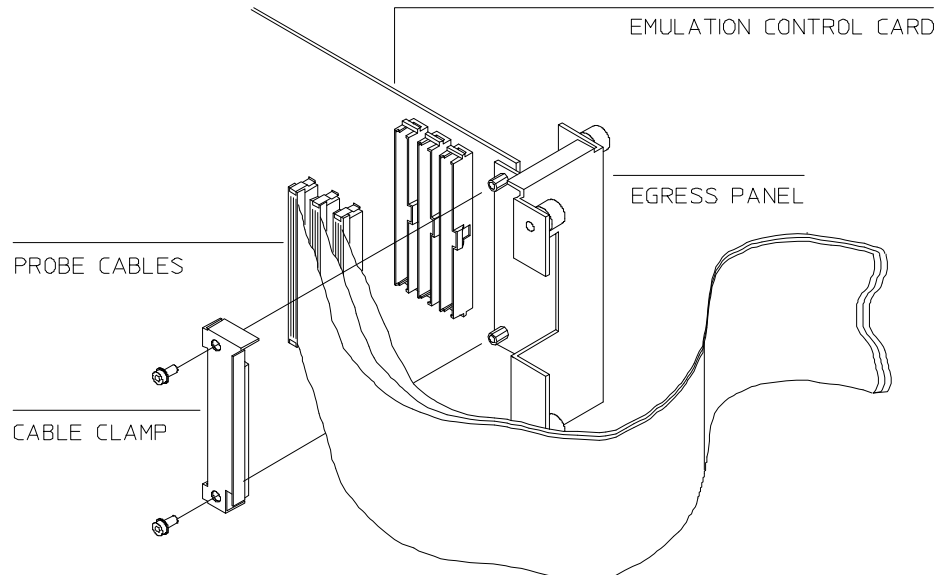
Before performing the tasks described in this chapter, you should be familiar with how the emulator operates in general. Refer to the *Concepts of Emulation and Analysis* manual and the "Getting Started" chapter of this manual.

---

## Installing the Emulation Probe Cable

The probe cables consist of three ribbon cables. The longest cable connects to J3 of the emulation control card, and to J3 of the probe. The shortest cable connects to J1 of the emulation control card and J1 of the probe. The ribbon cables are held in place on the emulation control card by a cable clamp attached with two screws. No clamp holds the ribbon cables in the probe.

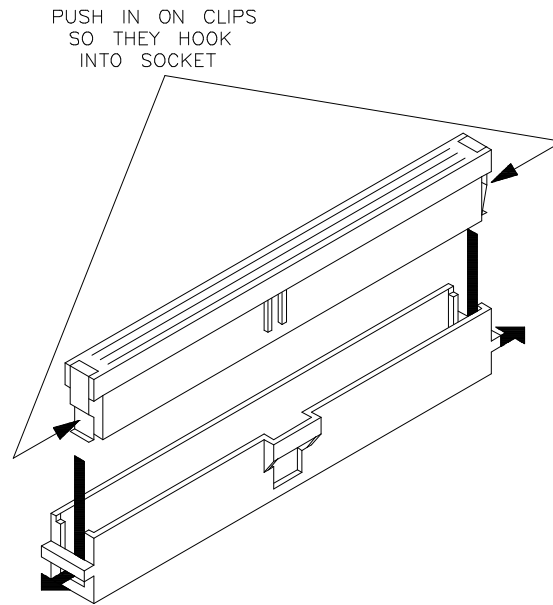
1. Secure the cable on the emulation control card with cable clamp and two screws.



**Figure 3-1 Installing cables to the control board**

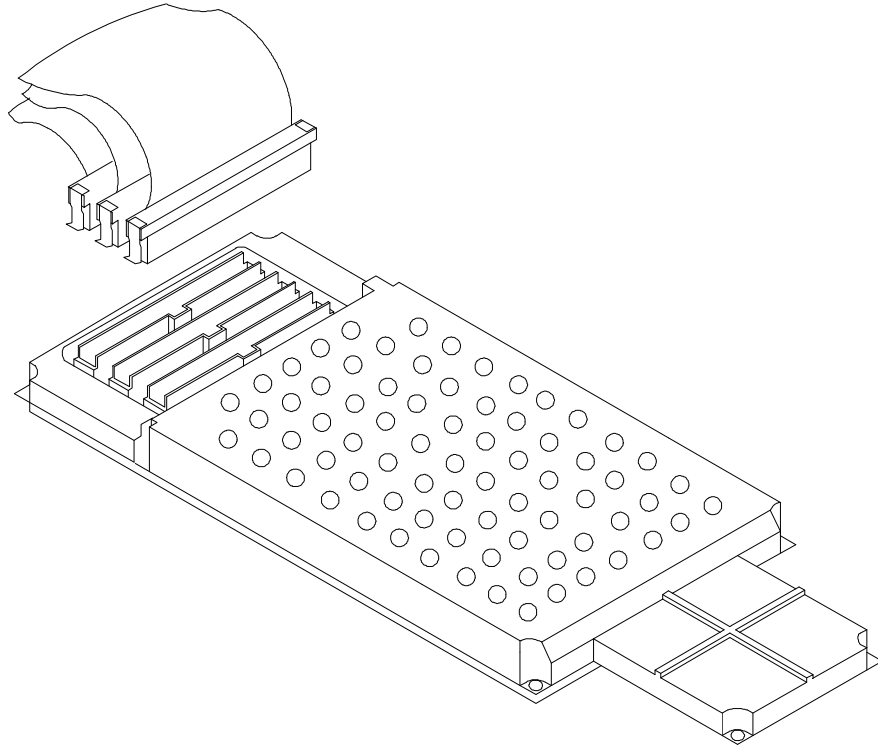
### 3-2 In-Circuit Emulation

2. When insert the ribbon cables into the appropriate sockets, press inward on the connector clips so that they into the sockets as shown.



**Figure 3-2 Installing cables into cable sockets**

3. Connect the other ends of the cables to the emulation probe.



**Figure 3-3 Installing cables to the emulation probe**

### **3-4 In-Circuit Emulation**

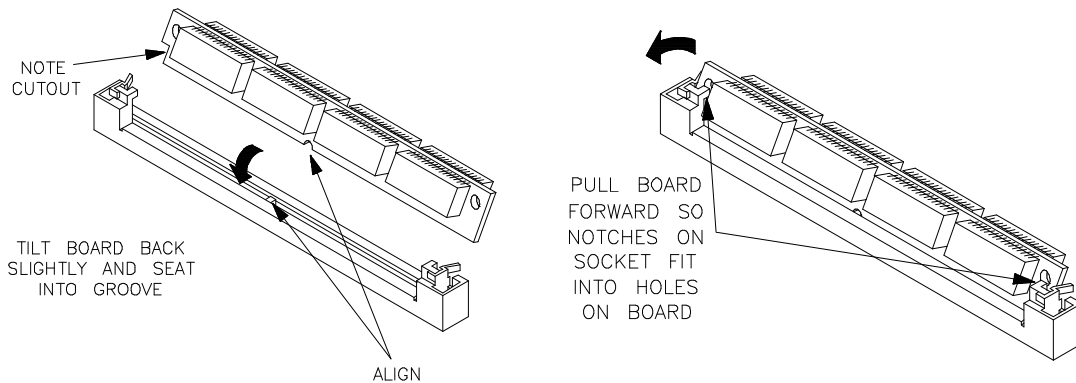
---

## Installing the Emulation Memory Module

There are three types of emulation memory modules that can be inserted into sockets on the probe.

1. Remove plastic rivets that secure the plastic cover on the top of the emulator probe, and remove the cover. The bottom cover is only removed when you need to replace a defective active probe on the exchange program.
2. Insert emulation memory module on the emulation probe. There is a cutout on one side of the memory modules so that they can only be installed one way.

To install memory modules, place the memory module into the socket groove at an angle. Firmly press the memory module into the socket to make sure it is completely seated. Once the memory module is seated in the connector groove, pull the memory module forward so that the notches on the socket fit into the holes on the memory module. There are two latches on the sides of the socket that hold the memory module in place.



**Figure 3-4 Installing the memory module**

3. Replace the plastic cover, and insert new plastic rivets to secure the cover.



---

## Installing into the Demo Target Board

To connect the microprocessor connector to the demo target board, proceed with the following instructions.

1. Remove front bezel and connect the power cable to the connector of the HP 64700B front panel. Refer to the *HP 64700 Series Installation/Service* manual.
2. Set up the processor mode switches on the demo target board. You need to set up switches to proper mode which you set up in the emulator configuration.
3. With HP 64700B power OFF, connect the emulation probe to the demo target board as shown in the Figure 4-5. When you install the probe into the demo target board, be careful not to bend any of the pins.
4. Connect the power cable supply wires from the emulator to demo target board. When attaching the wire cable to the demo target board, make sure the connector is aligned properly so that all three pins are connected.

---

### Note



Set up the processor mode switches equal to the processor mode set up in the emulator configuration.

---

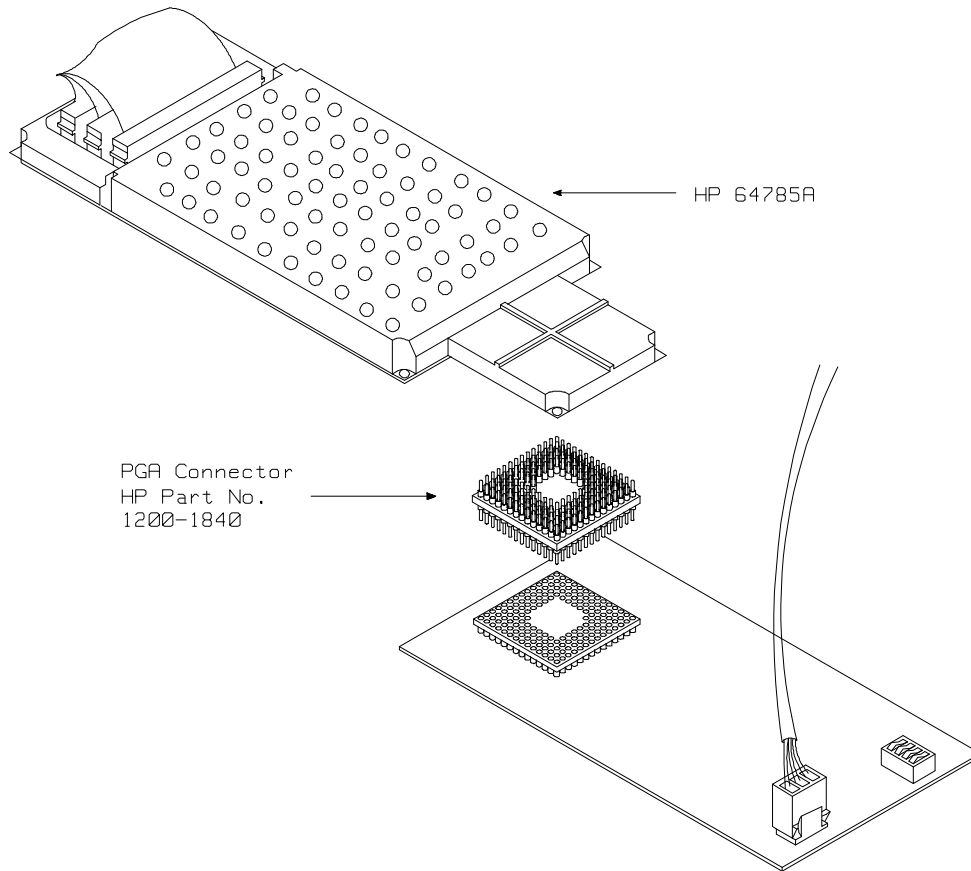
---

### Note



You need to attach the demo target board to the SH-7000 emulator, when you test the SH-7000 emulator using **pv** command.

---



**Figure 3-5 Installing the demo target board**

---

## Installing into a Target System

The SH-7000 emulation probe has a 135-pin PGA connector; The emulation probe is also provided with a conductive pin protector to protect the delicate gold-plated pins of the probe connector from damage due to impact.

---

### Caution



**Protect against electrostatic discharge.** The emulation probe contains devices that are susceptible to damage by electrostatic discharge. Therefore, precautionary measures should be taken before handling the microprocessor connector attached to the end of the probe cable to avoid damaging the internal components of the probe by electrostatic electricity.

---

### Caution



**Make sure target system power is OFF.** Do not install the emulation probe into the target system microprocessor socket with power applied to the target system. The emulator may be damaged if target system power is not removed before probe installation.

---

### Caution



**Make sure pin 1 of probe connector is aligned with pin 1 of the socket.** When installing the emulation probe, be sure that probe is inserted into the processor socket so that pin 1 of the connector aligns with pin 1 of the socket. Damage to the emulation probe will result if the probe is incorrectly installed.

---

### Caution



**DO NOT use the microprocessor connector without using a pin protector.** The pin protector prevents damage to the probe when inserting and removing the probe from the flexible adapter.

---

## **QFP socket/adaptor**

The QFP socket/adaptor is provided with the SH-7000 emulator. QFP socket/adaptor is designed for SH-7000 QFP microprocessor. To do in-circuit emulation, you must attach the QFP socket/adaptor to your target system and connect with the SH-7000 emulation probe.

### **Note**



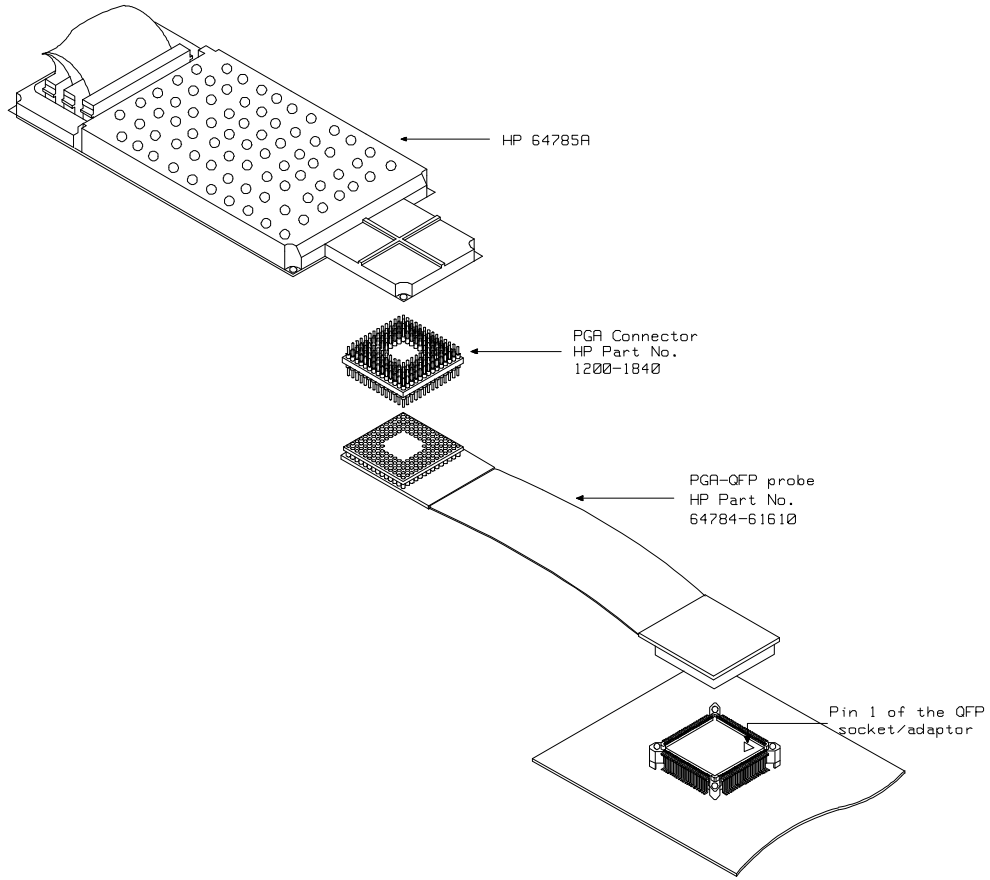
---

You can order additional QFP socket/adaptor with part No. HP 64784-61611. Contact your local HP sales representative to purchase additional parts.

---

## **Installing the emulation probe into your target system**

1. Attach the QFP socket/adaptor to your target system.
2. With HP 64700B power OFF, connect the PGA-QFP probe to the emulation probe through the PGA connector.
3. Power OFF your target system, and install the PGA-QFP probe to the QFP socket/adaptor as shown in Figure 4-6.
4. Power ON the emulator first, then power ON your target system.



**Figure 3-6 Installing into a target system board**

### **3-10 In-Circuit Emulation**

---

## In-Circuit configuration

The SH-7000 emulator provides configuration options for the following in-circuit emulation issues. Refer to the "Configuring the Emulator" chapter for more information.

### Specifying the pin function of PA8/ $\overline{\text{BREQ}}$ .

You need to specify whether your target system uses PA8 or  $\overline{\text{BREQ}}$  for PA8/ $\overline{\text{BREQ}}$  pin. By default, this configuration is set to "PA8".

---

## Runnig the emulation from Target Reset

You can specify that the SH-7000 emulator begins execution from target system reset. When the target system RES line becomes active and then inactive, the SH-7000 emulator will start reset sequence as actual microprocessor.

To specify a run from target system reset, enter the following commnad:

```
run from reset
```

The status now shows that the SH-7000 emulator is "Awaiting target reset". After the target system is reset, the status line message will change to show the appropriate emulator status.

### Note



---

In the "Awaiting target reset" status, you can not break into the monitor. If you exit this status, you need to enter "rst" command.

---

### Note



---

You need to break into monitor before running from reset, when you configure 'processor type' in situations where the emulator can not break.

---

---

## Reset Types

SH-7000 has two types of resets: power-on reset and manual reset. As Table 4-1 shows, to power OFF the target system always drives the SH-7000 emulator into the power-on reset state. Also, when power ON the target system, a high input at the NMI pin drives the SH-7000 emulator into power-on reset state and a low input at the NMI pin drives the emulator into manual reset state.

**Table 4-1 Reset Types**

Reset Types	Target System Power		
	OFF	ON	
		NMI	
		High	Low
Power-on reset	O	O	X
Manual reset	X	X	O

---

## Target System Interface and Timing Specification

Refer to the *SH-7000 Terminal Interface User's Guide* for information on the target system interface and timing specification of the SH-7000 emulator.

## Configuring the Emulator

---

### Introduction

Your SH-7000 emulator can be used in all stages of target system development. For instance, you can run the emulator out-of-circuit when developing target system software, or you can use the emulator in-circuit when integrating software with target system hardware. Emulation memory can be used in place of, or along with, target system memory. You can execute target programs in real-time or allow emulator execution to be diverted into the monitor when commands request access of target system resources (target system memory, register contents, etc.)

The emulator is a flexible instrument and it may be configured to suit your needs at any stage of the development process. This chapter describes the options available when configuring the SH-7000 emulator.

The configuration options are accessed with the following command.

*modify configuration* <RETURN>

After entering the command above, you will be asked questions regarding the emulator configuration. The configuration questions are listed below and grouped into the following classes.



**General Emulator Configuration:**

- Restricting to real-time execution.
- Selecting processor type.
- Specifying processor operation mode.
- Specifying Area 1 memory type.

**Memory Configuration:**

- Mapping memory.

**Emulator Pod Configuration:**

- Enabling quick-break mode.
- Specifying reset value for stack pointer.
- Selecting memory access size.
- Selecting PA8/BREQ pin function.

**Debug/Trace Configuration:**

- Enabling breaks on writes to ROM.
- Enabling setting breakpoints at delay slot.
- Specifying tracing of user program/emulation monitor cycles.
- Enabling tracing on-chip DMAC cycles.
- Enabling tracing refresh cycles.
- Selecting emulation analyzer speed.

**Simulated I/O Configuration:** Simulated I/O is described in the *Simulated I/O* reference manual.

**Interactive Measurement Configuration:** See the chapter on coordinated measurements in the *Softkey Interface Reference* manual.

## 4-2 Configuring the Emulator

---

## General Emulator Configuration

The configuration questions described in this section involve general emulator operation.

### Restrict to Real-Time Runs?

This configuration allows you to specify whether program execution should take place in real-time or whether commands should be allowed to cause breaks to the monitor during program execution.

- no** All commands, regardless of whether or not they require a break to the emulation monitor, are accepted by the emulator.
- yes** When runs are restricted to real-time and the emulator is running the user program, all commands that cause a break (except "reset", "break", "run", and "step") are refused. For example, the following commands are not allowed when runs are restricted to real-time:
- Display/modify registers.
  - Display/modify memory.

### Caution



---

If your target system circuitry is dependent on constant execution of program code, you should restrict the emulator to real-time runs. This will help insure that target system damage does not occur. However, remember that you can still execute the "reset", "break", and "step" commands; you should use caution in executing these commands.

---

## Processor type?

This question allows you to select which microprocessor to be emulated.

**7032**                    The SH-7032 microprocessor is emulated.

**7034**                    The SH-7034 microprocessor is emulated.

---

### Note



If the emulation processor without on-chip ROM is selected and the processor operation mode is configured as **mode\_2**, the emulator will ignore the mode configuration option and the emulation processor will be operated in **mode\_0**.

---

### Note



Changing this configuration setting will drive the emulator into a reset state and will reset the memory mapping.

---

### Note



When you change this configuration, you need to break into monitor once. Usually, changing this configuration will drive the emulator into monitor automatically, then drive it into a reset state. In situations without clock source, you need to break it, explicitly.

---

## Processor operation mode?

This configuration allows to you specify whether operation mode is single chip mode or external bus mode.

**mode\_0**                    The emulator will operate in mode 0.

**mode\_1**                    The emulator will operate in mode 1.

**mode\_2**                    The emulator will operate in mode 2.

## 4-4 Configuring the Emulator

**Note**



---

If **mode\_2** and the processor which has no on-chip ROM are selected, the emulator will ignore this mode configuration option and the emulation processor will be operated in **mode\_0**.

---

**Note**



---

When you configure to emulate **7032** microprocessor, **mode\_2** does not appear in this configuration item.

---

**Note**



---

You need to supply operation mode signal same as this configuration from the target system.

---

**Note**



---

Changing this configuration setting will drive the emulator into a reset state and will reset the memory mapping.

---

### Area 1 memory type?

This configuration allows you to select the memory type of the area1.

**dram**

If the area 1 is used as dynamic RAM space in your target system, set 'dram' to this configuration option. The memory mapper will treat the area 1 as 16-Mbyte address space.

**other**

If the area 1 is used as other memory space, set 'other' to this configuration option. The memory mapper will treat the area 1 as 4-Mbyte address space.

---

**Note**

---

Changing this configuration setting will drive the emulator into a reset state and will reset the memory mapping.

---

---

## Memory Configuration

The memory configuration questions allows you to select the monitor type, to select the location of the monitor, and to map memory. To access the memory configuration questions, you must answer "yes" to the following question.

### Modify memory configuration?

### Mapping Memory

The emulation memory consists of 256k, 1M, or 4Mbytes. You can define up to 16 memory range (at 16K byte boundaries and at least 16K byte length).

The memory mapper allows you to characterize memory locations. It allows you to specify whether a certain range of memory is present in the target system or whether you will be using emulation memory for that address range. You can also specify whether the target system memory is ROM or RAM, and you can specify that emulation memory be treated as ROM or RAM.

---

**Note**

---

The internal RAM/ROM area and all registers of on-chip peripheral modules are mapped automatically. And the emulation memory system does not introduce these areas in memory mapping display.

---

When you characterize memory ranges as emulation memory, note the following.

- When you use 1M byte memory module and characterize memory range which does not override 32K byte boundary as emulation memory, 64K byte is used.

Also when you use 4M byte memory module and characterize memory range which does not override 128K byte boundary, 128K byte is used.

**Note**



---

Direct memory access to the emulation memory by external DMAC is not allowed. Also, single address mode transfer to the emulation memory by internal DMAC is not allowed.

---

**Note**



---

The emulation memory has no parity bit. You can not check and generate parity for emulation memory.

---

**Note**



---

The SH-7000 emulator ignores memory mapping for address/data multiplexed I/O space. Address/data multiplexed I/O space is always accessed as target RAM. However, when you map this area as guarded memory, you can not access this area by commands.

---

Blocks of memory can also be characterized as guarded memory. Guarded memory accesses will generate "break to monitor" requests. Writes to ROM will generate "break to monitor" requests if the "Enable breaks on writes to ROM?" configuration item is enabled (see the "Debug/Trace Configuration" section which follows).

### **Determining the Locations to be Mapped**

Typically, assemblers generate relocatable files and linkers combine relocatable files to form the absolute file. The linker load map listing will show what locations your program will occupy in memory.

---

## Emulator Pod Configuration

To access the emulator pod configuration questions, you must answer "yes" to the following question.

### Modify emulator pod configuration?

#### Enable quick-break mode?

This question allows you to specify whether the quick-break is enabled or disabled.

**yes**

The emulator enables quick-break mode. In this configuration, temporary break to the monitor for an operation such as display registers will spend a very short time in the monitor. The CMB does not work in this setting.

**no**

The emulator disables quick-break mode. In this configuration, temporary break to the monitor will spend more time in the monitor.

#### Note



---

Changing this configuration setting will drive the emulator into a reset state.

---

#### Reset value for stack pointer?

Specify the value that the stack pointer will be set to when the monitor is entered after an emulation reset. This configuration option has no effect when a run from reset command is given.

The value of the stack pointer must be long word aligned.

#### Memory access size?

This configuration specifies the type of microprocessor cycles that are used by the monitor program to access memory locations. When a command requests the monitor to read or write to memory location, the monitor program will look at the access mode setting to determine whether byte or word instructions should be used.

<b>bytes</b>	Selecting the byte access mode specifies that the emulator will access memory using byte cycles (one byte at a time).
<b>words</b>	Selecting the word access mode specifies that the emulator will access memory using word cycles (one word at a time).
<b>any</b>	Selecting the any access mode specifies that the emulator will access memory using a display/modify memory command option. If option "long" is specified, access size will be set to "words". Other memory commands such as "load" and "store" will use an access size of "bytes".

**Note**




---

When the access size is **words**, modifying memory will fail if you try to modify memory from odd address or with data which byte count is odd. Also, you can't load file which byte count is odd. Therefore, it is recommended to use the emulator with default **any** or **bytes** in this configuration.

---

**PA8/BREQ pin function?**

This configuration option specifies the function of PA8/BREQ pin.

<b>breq</b>	If the PA8/BREQ pin is used as /BREQ input in your target system, set 'breq' to this configuration option.
<b>pa8</b>	If the PA8/BREQ pin is used as PA8 input/output or is not used in your target system, set 'pa8' to this configuration option.



---

## Debug/Trace Configuration

The debug/trace configuration questions allows you to specify breaks on writes to ROM, enable/disable the software breakpoints feature, and specify that the analyzer trace foreground/background execution. To access the debug/trace configuration questions, you must answer "yes" to the following question.

### Modify debug/trace options?

#### Break Processor on Write to ROM?

This question allows you to specify that the emulator break to the monitor upon attempts to write to memory space mapped as ROM. The emulator will prevent the processor from actually writing to memory mapped as emulation ROM; however, they cannot prevent writes to target system RAM locations which are mapped as ROM, even though the write to ROM break is enabled.

- yes** Causes the emulator to break into the emulation monitor whenever the user program attempts to write to a memory region mapped as ROM.
- no** The emulator will not break to the monitor upon a write to ROM. The emulator will not modify the memory location if it is in emulation ROM.

#### Note



---

The **wrrom** trace command status option allows you to use "write to ROM" cycles as trigger and storage qualifiers. For example, you could use the following command to trace about a write to ROM:

```
trace about status wrrom <RETURN>
```

---

**Enable setting  
breakpoints at delay  
slot?**

A software breakpoint at delay slot causes slot invalid instruction exception in your program.

**yes** When setting software breakpoints at delay slot is enabled, you can set software breakpoints at any location.

**no** The breakpoint command will check if the instruction before the requested breakpoint address is a delayed branch or not. And, if the instruction is a delayed branch, the command will fail.

**Trace background or  
foreground  
operation?**

This configuration option allows you to specify whether the analyzer trace only user program, only monitor program or both monitor and user program.

**foreground** Specifies that the analyzer trace only user program cycles. This option is specified by the default emulation configuration.

**background** Specifies that the analyzer trace only monitor cycles. (This is rarely useful setting.)

**both** Specifies that the analyzer trace both user program and emulation monitor cycles. You may wish to specify this option so that all emulation processor cycles may be viewed in the trace display.

### Trace on-chip DMAC cycles?

This configuration option allows you to specify whether the analyzer trace on-chip DMAC cycles or not.

**yes** Specifies that the analyzer traces on-chip DMAC cycles.

**no** Specifies that the analyzer does not trace on-chip DMAC cycles.

#### Note



Address error by internal DMAC in monitor is suspended and occurs after when context is changed to user program.

#### Note



When trace on-chip DMAC cycles is no, the emulator will not break to monitor upon a write to ROM or guarded memory by internal DMAC.

### Trace refresh cycles?

This configuration option allows you to specify whether the analyzer trace refresh cycles or not.

**yes** Specifies that the analyzer traces refresh cycles.

**no** Specifies that the analyzer does not trace refresh cycles.

### Emulation analyzer speed?

This question allows you specify the emulation processor clock speed. The analyzer capabilities of time and state count are affected by the processor clock speed. You must answer this question, when you use HP 64704A emulation bus analyzer.

**slow** Specifies the processor clock speed is less than or equal to 16.6MHz. Both state and time counting are available.

**fast** Specifies the processor clock speed is greater than 16.6MHz. Only state counting are available.

---

## Simulated I/O Configuration

The simulated I/O feature and configuration options are described in the *Simulated I/O* reference manual.

---

## Interactive Measurement Configuration

The interactive measurement configuration questions are described in the chapter on coordinated measurements in the *Softkey Interface Reference* manual. Examples of coordinated measurements that can be performed between the emulator and the emulation analyzer are found in the "Using the Emulator" chapter.

---

## Saving a Configuration

The last configuration question allows you to save the previous configuration specifications in a file which can be loaded back into the emulator at a later time.

### Configuration file name? <FILE>

The name of the last configuration file is shown, or no filename is shown if you are modifying the default emulator configuration.

If you press <RETURN> without specifying a filename, the configuration is saved to a temporary file. This file is deleted when you exit the Softkey Interface with the "end release\_system" command.

When you specify a filename, the configuration will be saved to two files; the filename specified with extensions of ".EA" and ".EB". The file with the ".EA" extension is the "source" copy of the file, and the file with the ".EB" extension is the "binary" or loadable copy of the file.

Ending out of emulation (with the "end" command) saves the current configuration, including the name of the most recently loaded configuration file, into a "continue" file. The continue file is not normally accessed.

---

## Loading a Configuration

Configuration files which have been previously saved may be loaded with the following Softkey Interface command.

*load configuration* <FILE> <RETURN>

This feature is especially useful after you have exited the Softkey Interface with the "end release\_system" command; it saves you from having to modify the default configuration and answer all the questions again. To reload the current configuration, you can enter the following command.

*load configuration* <RETURN>

## Using the Emulator

---

### Introduction

The "Getting Started" chapter shows you how to use the basic

This chapter discuss:

- Register names and classes
- Hardware breakpoint
- Analyzer topics
  - Specifying data for trigger or store condition
- Features available via "pod\_command"

This chapter shows you how to:

Emulation memory access

- Store the contents of memory into absolute files
- Make coordinated measurements

---

## REGISTER CLASS and NAME

**Summary** SH-7000 register designator. All available register class names and register names are listed below.

<REG\_CLASS>

<REG\_NAME> Description

\*(All basic registers)

<b>PC</b>	Program counter
<b>SR</b>	Status register
<b>R0</b>	General register R0
<b>R1</b>	General register R1
<b>R2</b>	General register R2
<b>R3</b>	General register R3
<b>R4</b>	General register R4
<b>R5</b>	General register R5
<b>R6</b>	General register R6
<b>R7</b>	General register R7
<b>R8</b>	General register R8
<b>R9</b>	General register R9
<b>R10</b>	General register R10
<b>R11</b>	General register R11
<b>R12</b>	General register R12
<b>R13</b>	General register R13
<b>R14</b>	General register R14
<b>R15</b>	General register R15
<b>SP</b>	Stack pointer
<b>GBR</b>	Global base register
<b>VBR</b>	Vector base register
<b>PR</b>	Procedure register
<b>MACH</b>	Multiply and accumulate register high
<b>MACL</b>	Multiply and accumulate register low

### **INTC(Interrupt controller)**

<b>IPRA</b>	Interrupt priority register A
<b>IPRB</b>	Interrupt priority register B
<b>IPRC</b>	Interrupt priority register C
<b>IPRD</b>	Interrupt priority register D
<b>IPRE</b>	Interrupt priority register E
<b>ICR</b>	Interrupt control register

### **UBC(User break controller)**

<b>BAR</b>	Break address register
<b>BAMR</b>	Break address mask register
<b>BBR</b>	Break bus cycle register

### **BSC(Bus state controller)**

<b>BCR</b>	Bus control register
<b>WCR1</b>	Wait state control register 1
<b>WCR2</b>	Wait state control register 2
<b>WCR3</b>	Wait state control register 3
<b>DCR</b>	DRAM area control register
<b>PCR</b>	Parity control register
<b>RCR</b>	Refresh control register
<b>RTCSR</b>	Refresh timer control/status register
<b>RTCNT</b>	Refresh timer counter
<b>RTCOR</b>	Refresh time constant register

### **DMAC0(Direct memory access controller 0)**

<b>SAR0</b>	DMA source address register 0
<b>DAR0</b>	DMA destination register 0
<b>DMATCR0</b>	DMA transfer count register 0
<b>CHCR0</b>	DMA channel control register 0
<b>DMAOR</b>	DMA operation register



### **DMAC1(Direct memory access controller 1)**

<b>SAR1</b>	DMA source address register 1
<b>DAR1</b>	DMA destination register 1
<b>DMATCR1</b>	DMA transfer count register 1
<b>CHCR1</b>	DMA channel control register 1

### **DMAC2(Direct memory access controller 2)**

<b>SAR2</b>	DMA source address register 2
<b>DAR2</b>	DMA destination register 2
<b>DMATCR2</b>	DMA transfer count register 2
<b>CHCR2</b>	DMA channel control register 2

### **DMAC3(Direct memory access controller 3)**

<b>SAR3</b>	DMA source address register 3
<b>DAR3</b>	DMA destination register 3
<b>DMATCR3</b>	DMA transfer count register 3
<b>CHCR3</b>	DMA channel control register 3

### **ITUG(Integrated-timer pulse unit general)**

<b>TSTR</b>	Timer start register
<b>TSNC</b>	Timer synchro register
<b>TMDR</b>	Timer mode register
<b>TFCR</b>	Timer function control register
<b>TOCR</b>	Timer output control register

### **ITU0(Integrated-timer pulse unit 0)**

<b>TCR0</b>	Timer control register 0
<b>TIOR0</b>	Timer I/O register 0
<b>TIER0</b>	Timer interrupt enable register 0
<b>TSR0</b>	Timer status register 0
<b>TCNT0</b>	Timer counter 0
<b>GRA0</b>	General register A0
<b>GRB0</b>	General register B0

### **ITU1(Integrated-timer pulse unit 1)**

<b>TCR1</b>	Timer control register 1
<b>TIOR1</b>	Timer I/O register 1
<b>TIER1</b>	Timer interrupt enable register 1
<b>TSR1</b>	Timer status register 1
<b>TCNT1</b>	Timer counter 1
<b>GRA1</b>	General register A1
<b>GRB1</b>	General register B1

### **ITU2(Integrated-timer pulse unit 2)**

<b>TCR2</b>	Timer control register 2
<b>TIOR2</b>	Timer I/O register 2
<b>TIER2</b>	Timer interrupt enable register 2
<b>TSR2</b>	Timer status register 2
<b>TCNT2</b>	Timer counter 2
<b>GRA2</b>	General register A2
<b>GRB2</b>	General register B2

### **ITU3(Integrated-timer pulse unit 3)**

<b>TCR3</b>	Timer control register 3
<b>TIOR3</b>	Timer I/O register 3
<b>TIER3</b>	Timer interrupt enable register 3
<b>TSR3</b>	Timer status register 3
<b>TCNT3</b>	Timer counter 3
<b>GRA3</b>	General register A3
<b>GRB3</b>	General register B3

### **ITU4(Integrated-timer pulse unit 4)**

<b>TCR4</b>	Timer control register 4
<b>TIOR4</b>	Timer I/O register 4
<b>TIER4</b>	Timer interrupt enable register 4
<b>TSR4</b>	Timer status register 4
<b>TCNT4</b>	Timer counter 4
<b>GRA4</b>	General register A4
<b>GRB4</b>	General register B4

### **TPC(Programmable timing pattern controller)**

<b>TPMR</b>	TPC output mode register
<b>TPCR</b>	TPC output control register
<b>NDERA</b>	Next data enable register A
<b>NDERB</b>	Next data enable register B
<b>NDRA</b>	Next data register A (address 5ffff5H)
<b>NDRA0</b>	Next data register A (address 5ffff7H)
<b>NDRB</b>	Next data register B (address 5ffff4H)
<b>NDRB2</b>	Next data register B (address 5ffff6H)

### **WDT(Watchdog timer)**

<b>WDTCR</b>	Timer control/status register
<b>WDTCNT</b>	Timer counter
<b>RSTCSR</b>	Reset control/status register

### **SCI0(Serial communication interface 0)**

<b>SMR0</b>	Serial mode register 0
<b>BRR0</b>	Bit rate register 0
<b>SCR0</b>	Serial control register 0
<b>TDR0</b>	Transmit data register 0
<b>SSR0</b>	Serial status register 0
<b>RDR0</b>	Receive data register 0 (Read Only)

### **SCI1(Serial communication interface 1)**

<b>SMR1</b>	Serial mode register 1
<b>BRR1</b>	Bit rate register 1
<b>SCR1</b>	Serial control register 1
<b>TDR1</b>	Transmit data register 1
<b>SSR1</b>	Serial status register 1
<b>RDR1</b>	Receive data register 1 (Read Only)

#### **ADC(A/D converter)**

<b>ADDRA</b>	A/D data register A	(Read Only)
<b>ADDRB</b>	A/D data register B	(Read Only)
<b>ADDRC</b>	A/D data register C	(Read Only)
<b>ADDRD</b>	A/D data register D	(Read Only)
<b>ADDSR</b>	A/D control/status register D	
<b>ADCR</b>	A/D control register	

#### **PFC(Pin function controller)**

<b>PAIOR</b>	Port A I/O register	
<b>PBIOR</b>	Port B I/O register	
<b>PACR1</b>	Port A control register 1	
<b>PACR2</b>	Port A control register 2	
<b>PBCR1</b>	Port B control register 1	
<b>PBCR2</b>	Port B control register 2	
<b>CASCR</b>	Column address strobe pin control register	

#### **PORT(Parallel I/O port)**

<b>PADR</b>	Port A data register	
<b>PBDR</b>	Port B data register	
<b>PCDR</b>	Port C data register	

#### **SYS(System control)**

<b>SBYCR</b>	System control register	
--------------	-------------------------	--

---

## Hardware Breakpoints

The analyzer may generate a break request to the emulation processor. To break when the analyzer trigger condition is satisfied, use the "break\_on\_trigger" trace option.

Additionally, you can see the program states before the breakpoint in trace listing. Specify the trigger position at the end of trace listing by using "before" option.

When the trigger condition is found, the emulator execution will break into the emulation monitor. Then you can also see the trace listing mentioned above, enter the following commands.

```
trace before <QUALIFIER>  
break_on_trigger<RETURN>
```

Without the trigger condition, the trigger will never occur and will never break.

---

## Analyzer Topics

### Specifying Data for Trigger or Store Condition

You may want to trigger the emulation analyzer when specific data appears on the data bus. You can accomplish this with the following command.

```
trace after data <data>
```

There are some points to be noticed when you trigger the analyzer to 32 bits bus area in this way. You need to specify the <data> with 32 bits value shown in Table 5-1. This is because the analyzer is designed so that it can capture data on internal data bus (which has 32 bits width).

**Table 5-1 Trigger for 32 bit bus area**

Address Value	Byte Access	Word Access
4N <sup>*1</sup>	ddxxxxxx <sup>*2</sup>	ddddxxxx <sup>*2</sup>
4N+1 <sup>*1</sup>	0xxddxxxx <sup>*2</sup>	-
4N+2 <sup>*1</sup>	0xxxxddxx <sup>*2</sup>	0xxxxddd <sup>*2</sup>
4N+3 <sup>*1</sup>	0xxxxxxdd <sup>*2</sup>	-

\*1 N means random value

\*2 dd and dddd mean data value

Note that you always need to specify "xx" value to identify byte/word values on the 32 bit data bus. Be careful to trigger the analyzer by data.

When you trigger the analyzer to 8/16 bits bus area, you can capture same way as the SH-7000 microprocessor.

---

## Features Available via Pod Commands

Several emulation features available in the Terminal Interface but not in the Softkey Interface may be accessed via the following emulation commands.

```
display pod_command <RETURN>
pod_command '<Terminal Interface command>'
<RETURN>
```

Some of the most notable Terminal Interface features not available in the Softkey Interface are:

- Searching memory for strings or numeric expressions.
- Sequencing in the analyzer.

Refer to your Terminal Interface documentation for information on how to perform these tasks.

## Note



---

Be careful when using the "pod\_command". The Softkey Interface, and the configuration files in particular, assume that the configuration of the HP 64700 pod is NOT changed except by the Softkey Interface. Be aware that what you see in "modify configuration" will NOT reflect the HP 64700 pod's configuration if you change the pod's configuration with this command. Also, commands which affect the communications channel should NOT be used at all. Other commands may confuse the protocol depending upon how they are used. The following commands are not recommended for use with "pod\_command":

**stty, po, xp** - Do not use, will change channel operation and hang.  
**echo, mac** - Usage may confuse the protocol in use on the channel.  
**wait** - Do not use, will tie up the pod, blocking access.  
**init, pv** - Will reset pod and force end release\_system.  
**t** - Do not use, will confuse trace status polling and unload.0h)0

---

---

## Accessing Emulation Memory

Usually, the emulation memory is accessed by monitor program. Even if the emulation is reset state, the emulation memory can be accessed.

---

## Storing Memory Contents to an Absolute File

The "Getting Started" chapter shows you how to load absolute files into emulation or target system memory. You can also store emulation or target system memory to an absolute file with the following command.

```
store memory 800h thru 84fh to absfile  
<RETURN>
```

The command above causes the contents of memory locations 800H-84FH to be stored in the absolute file "absfile.X". Notice that the ".X" extension is appended to the specified filename.

---

## Coordinated Measurements

For information on coordinated measurements and how to use them, refer to the "Coordinated Measurements" chapter in the *Softkey Interface Reference* manual.



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## Notes

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